



KinWrite: Handwriting-based Authentication Using Kinect

Jing Tian*, Chengzhang Qu **, Wenyuan Xu* and Song Wang*

*Dept. of Computer Science and Engineering, University of South Carolina

**School of Computer Science, Wuhan University

Roadmap

- ❑ Authentication Background
- ❑ KinWrite Framework
 - ✦ Data processing
 - ✦ Enrollment & Verification
- ❑ Experiments
 - ✦ Legitimate users
 - ✦ Attackers
- ❑ Conclusions & On-going work

Authentication Background

- ❑ What you know – text passwords
 - ✦ What is secure is hard to remember
- ❑ What you own – token
 - ✦ Lost or stolen token
- ❑ Who you are – Physical biometrics
 - ✦ Limited number

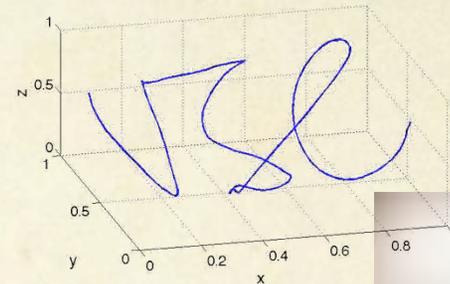
Goal: address all the limitation.



Our Solution: *3D-Signature*

❑ **3D signature:** *handwriting in 3D space*

- ✦ Write **short, easy to remember** passwords in the space,
 - ✧ 2 or 3 characters
- ✦ Behavioral biometrics:
 - ✧ Can be updated
 - ✧ Difficult to duplicate
 - ✧ A weak typed password can still be strong if it is written in 3D space



✦ Challenges:

- ✧ Change over time?
- ✧ Reject malicious users?
- ✧ Accept genuine users?

Our Solution: KinWrite

-- *Kinect + 3D-Signature*

❑ Microsoft Kinect

- ✦ A motion input RGB-D sensor
- ✦ Launched by Microsoft for Xbox 360 and Windows PCs

✦ Advantages

- ✧ Low cost
- ✧ Captures 3D information
 - ▷ Depth sensor
- ✧ Works in the dark

✦ Disadvantages

- ✧ Low resolution
- ✧ Measurement errors



KinWrite: Overview

Phase I: Enrollment

Register a username

Draw a signature
K times

Template
Generation

Phase II: Verification

Log in

Draw
a signature

Verification:
Pass / Fail

- Usability requirements
 - ✦ Rapid enrollment
 - ✦ Rapid verification
- Security requirement
 - ✦ Unforgeability

**3D Signatures should
be processed**

KinWrite: Data Processing

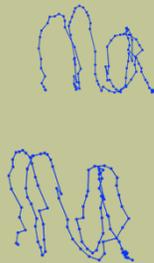
Data Processing

Data Acquisition



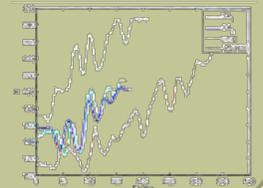
Preprocessing

1	2	3	4	
156	62	1542	130125570	
156	62	1542	130125582	
156	62	1542	130125644	
156	62	23000	1549	130125670
151.8000	62	6000	1549	130125708
151.8647	62	6647	1549	130125740
151	62	1542	130125772	
151.8000	62	6000	1549	130125804
156.5000	62	1540	130125836	
156.5000	62	1542	130125867	
156.5000	62	1540	130125899	
156.5000	62	1542	130125931	
146.5000	62	1540	130125964	
156.5000	62	1542	130125995	



Feature Extracting

Type	Features
Positions & Distance	$\mathbf{p}(t), d(t)$
Velocity	$\dot{\mathbf{p}}(t)$
Acceleration	$\ \ddot{\mathbf{p}}(t)\ $
Slope angle	$\theta_{xy}(t), \theta_{zx}(t),$
Path angle	$\alpha(t)$
Log radius of curvature	$\log \frac{1}{\kappa(t)}$



Enrollment

Verification

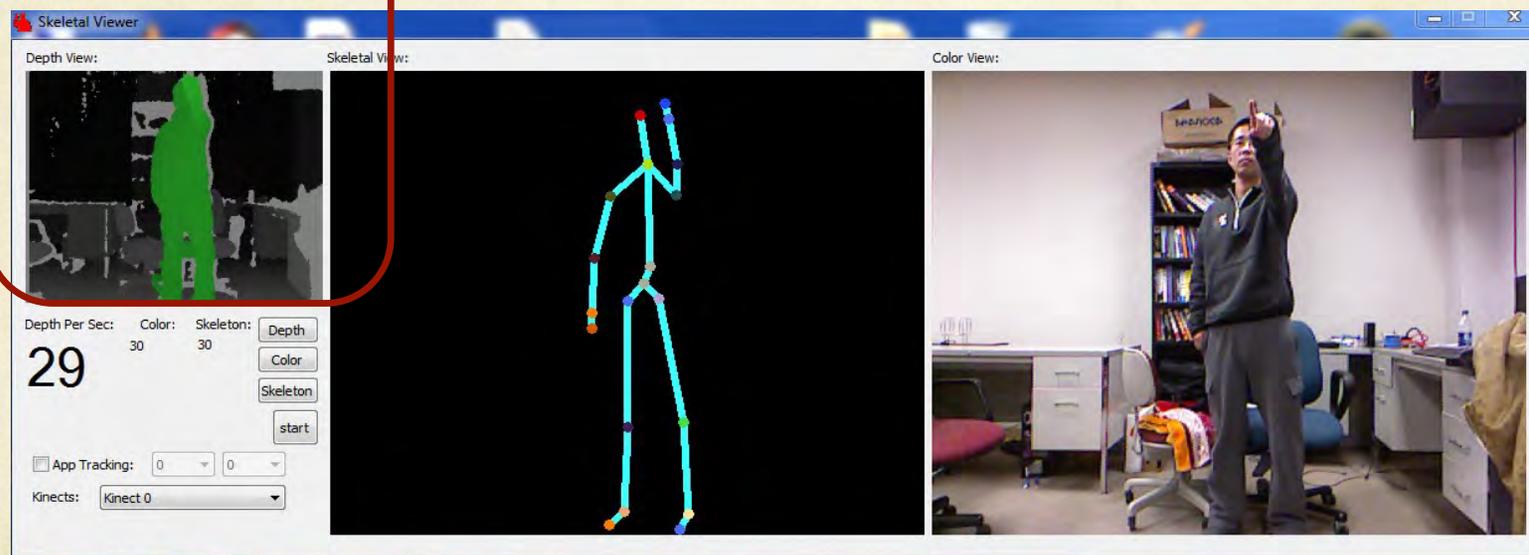
Data Processing: Acquisition

- ❑ Subject: raise a hand and use a fingertip
- ❑ Kinect: record the writing motion in the space

Depth frames

Skeleton points

RGB images



Data Acquisition

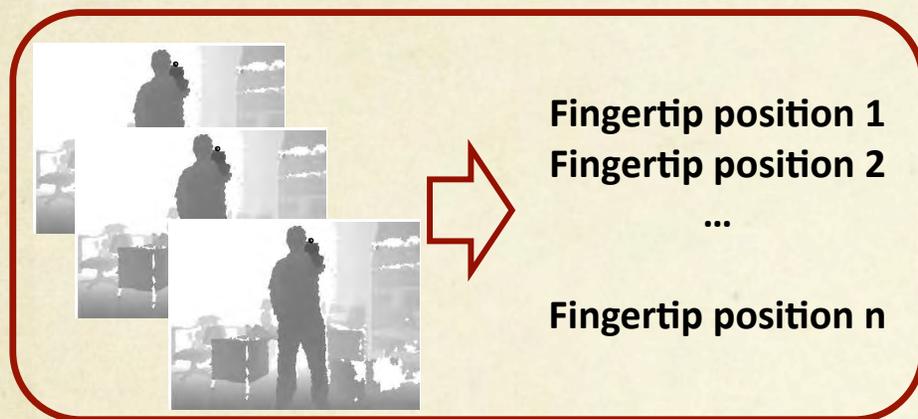


Data Preprocessing

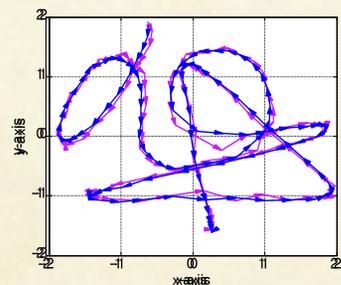
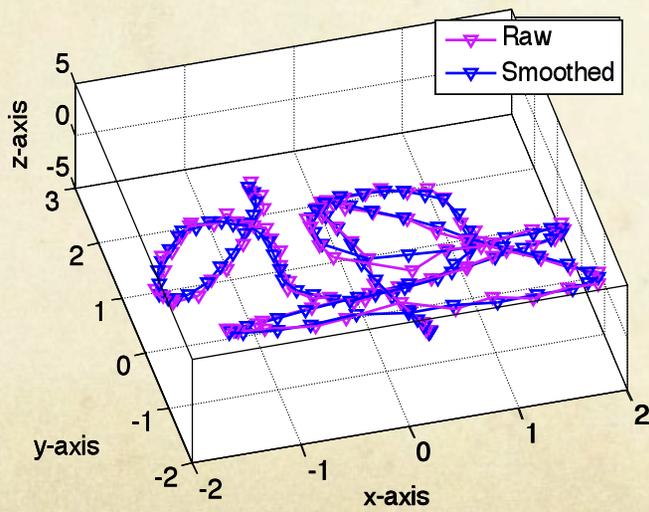


Feature Extracting

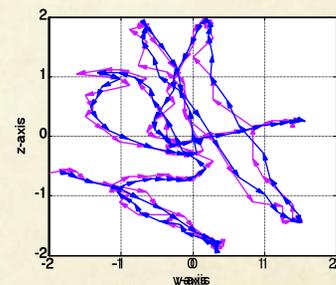
Data Processing: Preprocessing



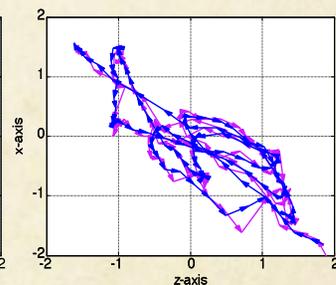
- ✦ Raw signatures
 - ✦ Noisy
- ✦ Smooth
 - ✦ Kalman filter



x-y plane



y-z plane

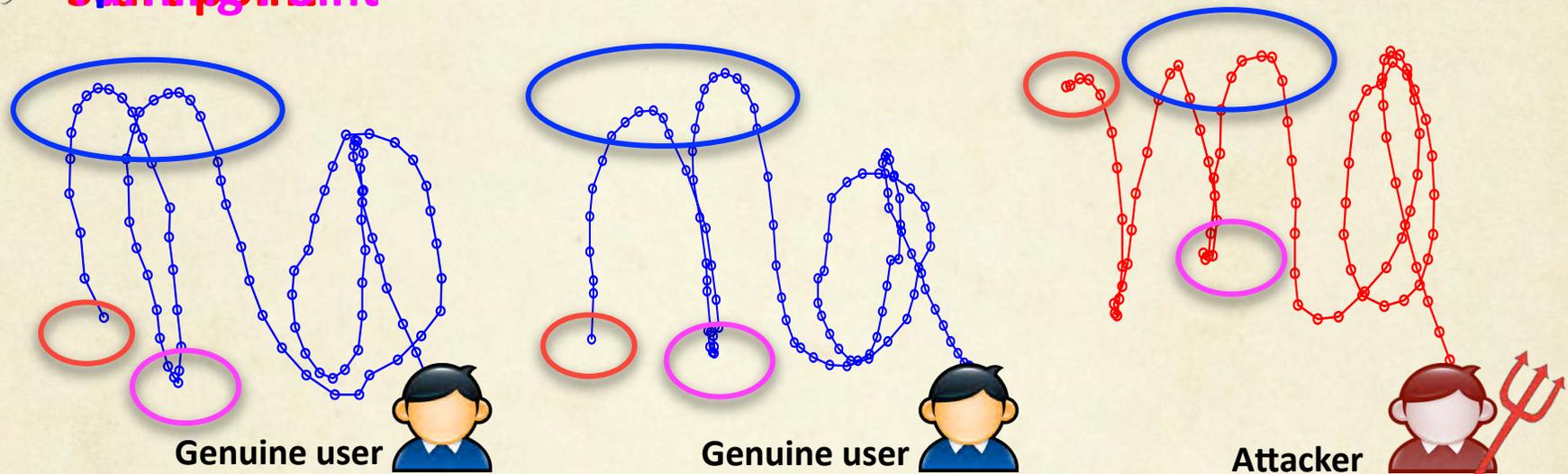


z-x plane



Data Processing: Feature Extracting

Speed Point



Type	Features
Positions & Distance	$\mathbf{p}(t), d(t)$
Velocity	$\dot{\mathbf{p}}(t)$
Acceleration	$\ \ddot{\mathbf{p}}(t)\ $
Slope angle	$\theta_{xy}(t), \theta_{zx}(t),$
Path angle	$\alpha(t)$
Log radius of curvature	$\log \frac{1}{\kappa(t)}$

← Six types 3D features

- Movement
- Geometry

Data Acquisition



Data Preprocessing

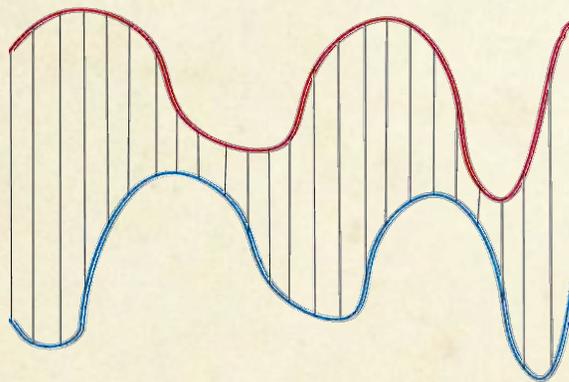


Feature Extracting

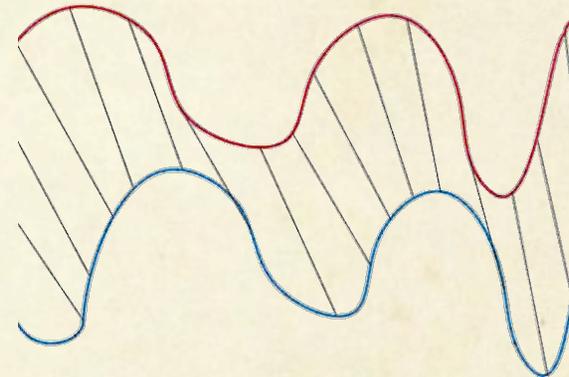
Quantify the similarity of 3D-signatures

Approach--Dynamic Time Warping (DTW)

- ✦ DTW distance represents the similarities between two 3D-signature samples --Warping along the temporal axis



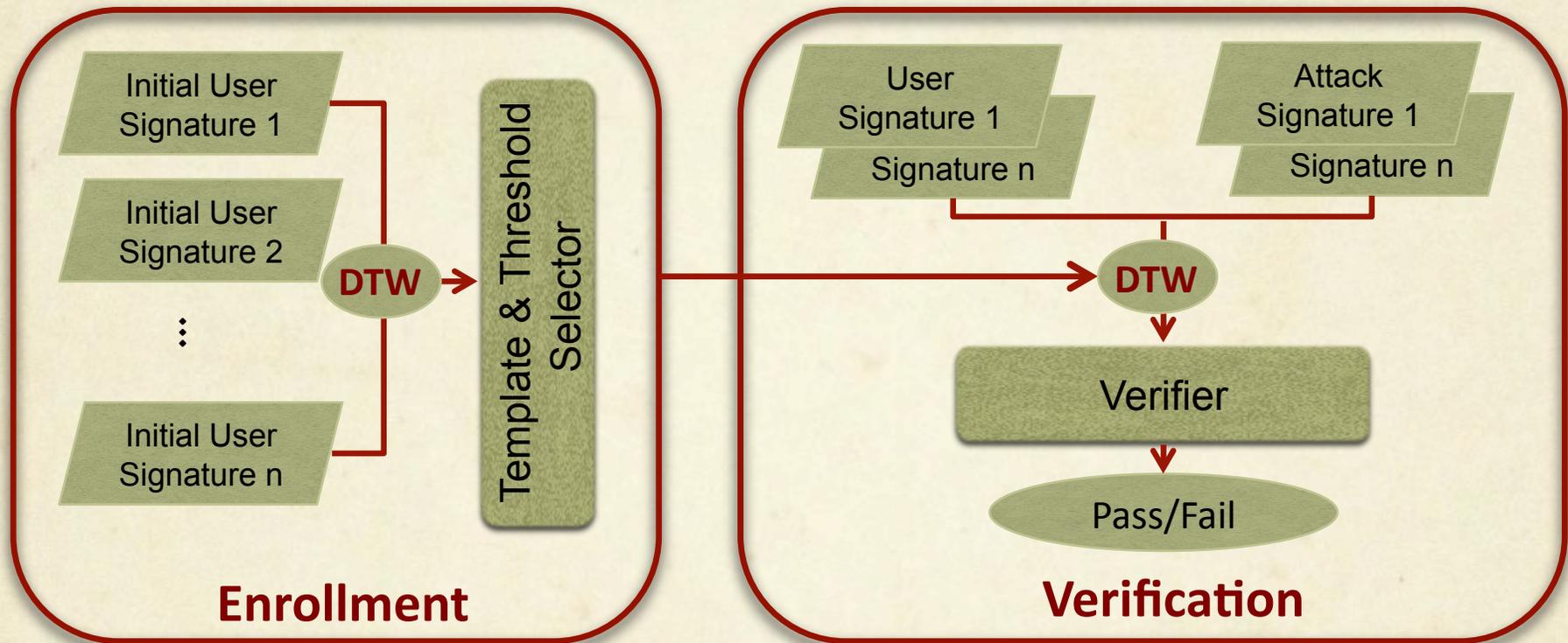
Euclidean Distance



Dynamic Time Warping

- ✦ Requires a small number of training samples

KinWrite: Enrollment & Verification



- ✦ **Template:** best represent the signature
- ✦ **Threshold:** determine whether two signatures are from the same user
 - ◇ DTW distance < threshold → pass
 - ◇ DTW distance > threshold → fail to pass

Experiments: Setup

□ Experiment setup

- ✦ 3 Kinect sensors
- ✦ Distance → 1.5 - 2.5 meters
- ✦ A sample → a video clip (2-12s),
~30 frames/second, depth frames



□ Evaluation metrics:

- ✦ *Precision* = verified genuine users / all verified users
 - ◇ Security
- ✦ *Recall* = verified genuine users / all genuine users
 - ◇ *Usability*
 - ◇ *Average attempts* = 1 / *Recall*

Experiments: Scenarios

❑ Scenario 1 – Legitimate users



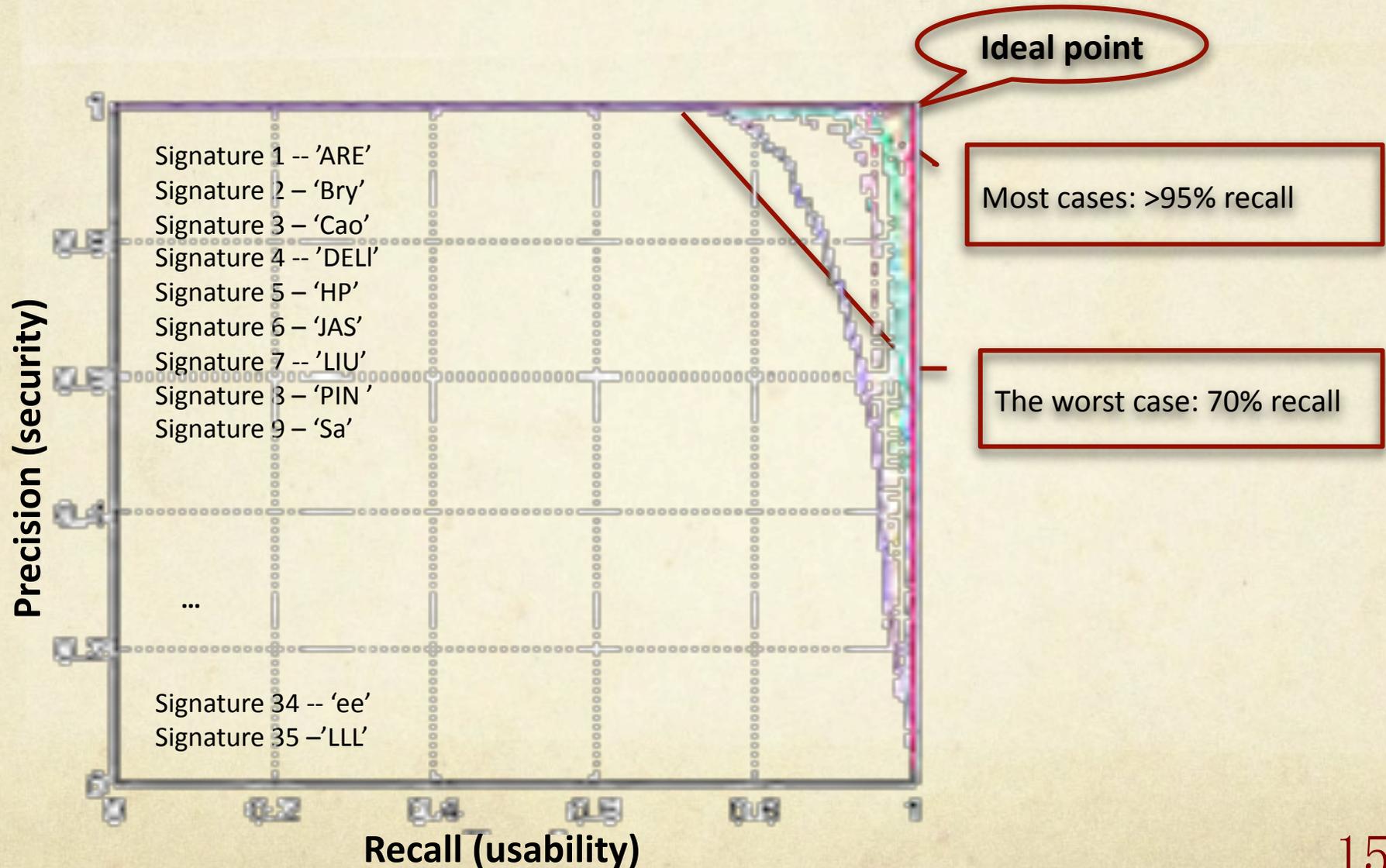
✦ Let the subjects write their genuine signatures:

✦ **18** users, **35** signatures

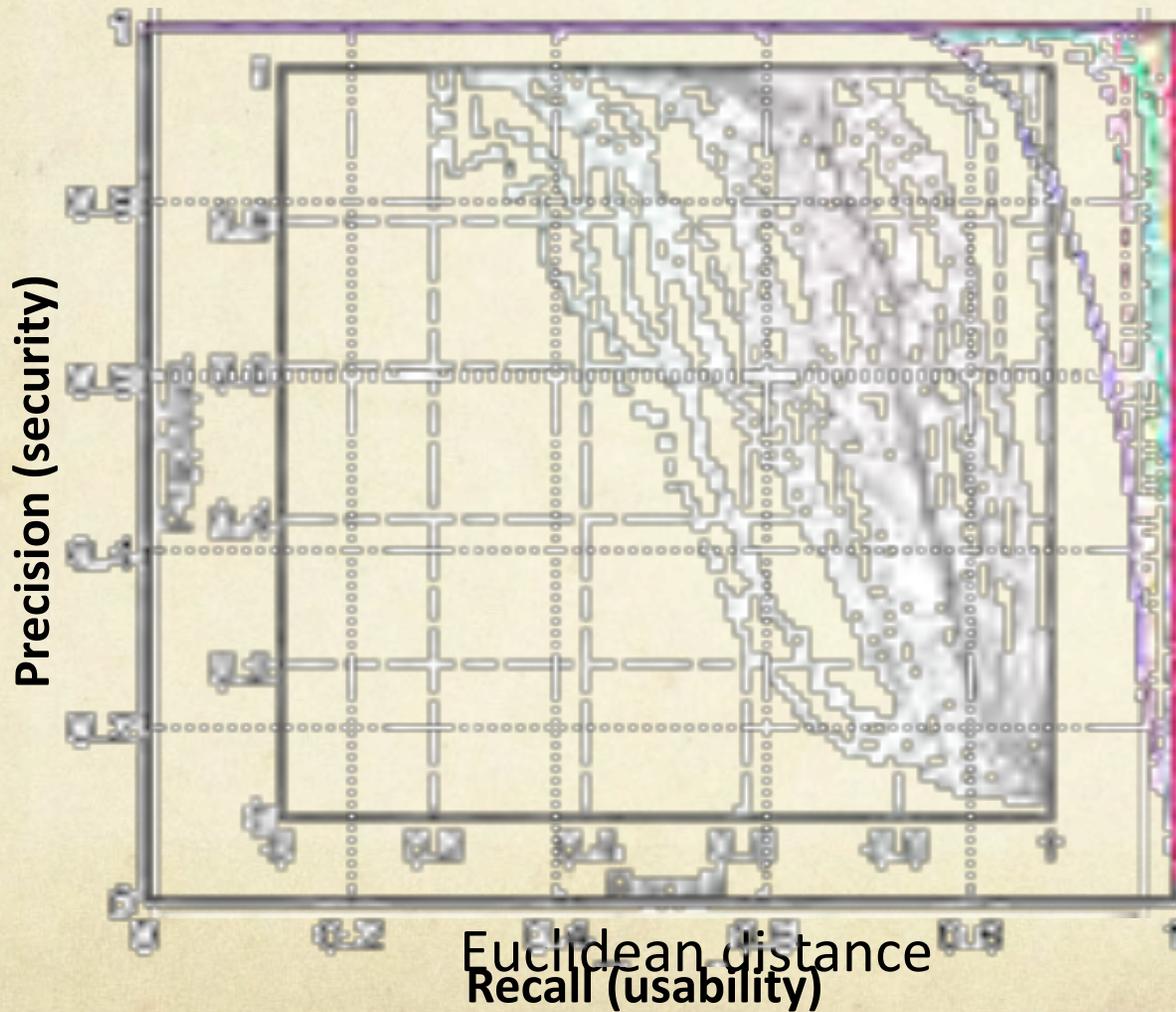
✦ **18 - 47** 3D-signature *samples* for each signature over a period of **5** months

✦ **1180** samples in total

Results: Legitimate Users



Results: Legitimate Users



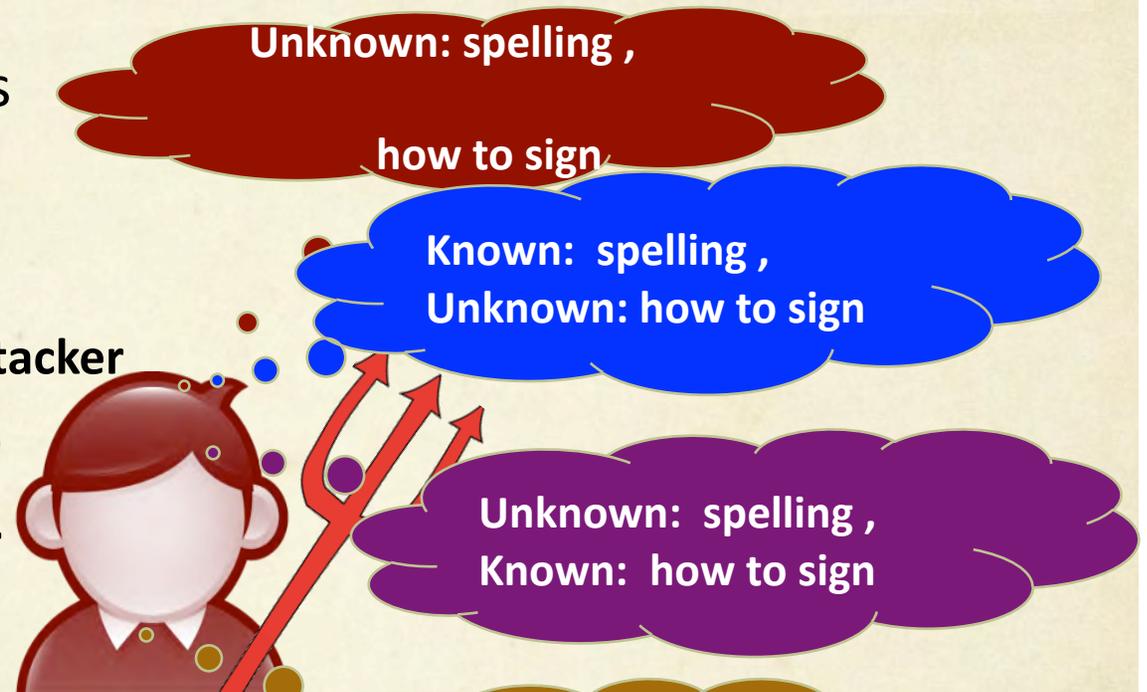
DTW

Experiments: Scenarios

Scenario 2 – Attackers

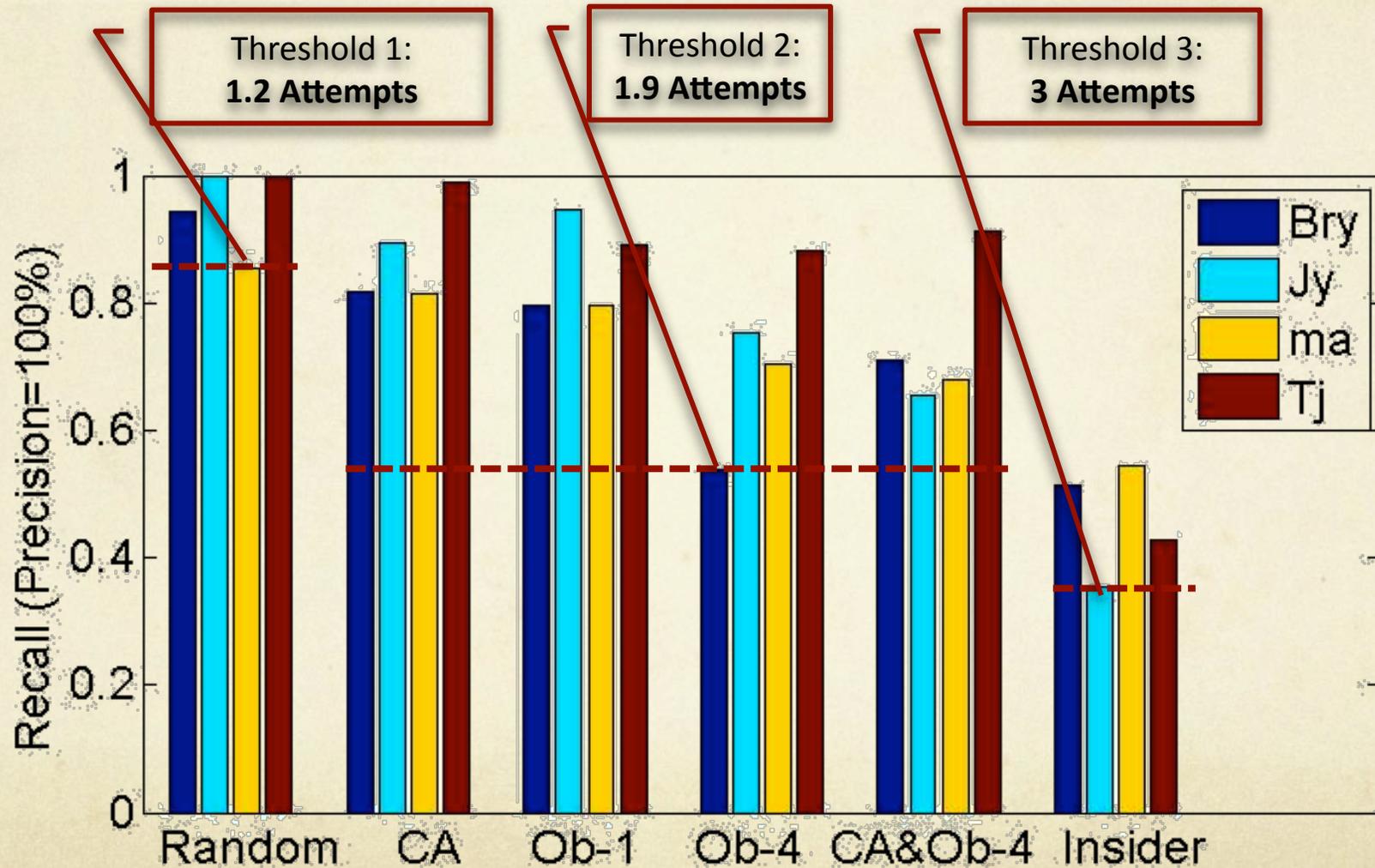
Attack model

- ✧ Random attacker
- ✧ Content-aware attacker
- ✧ Observer attacker
- ✧ Educated attacker
- ✧ Insider attacker



Attack Type	# 'attacker'	# samples from each	# 'victim'	# samples
Random Attack	34	14~42	4	1040
Content-Aware Attack	6	10	4	240
1-Observer Attack	12	5	4	240
4-Observer Attack	12	5	4	240
Educated Attack	12	5	4	240
Insider Attack	12	5	4	240

Results: Attack Scenarios



Conclusions and On-going Work

□ Conclusions

- ✦ Designed a behavior-based authentication system (KinWrite)
- ✦ Our experiment results based on over 2000 samples showed that 3D-signatures can be used to verify users

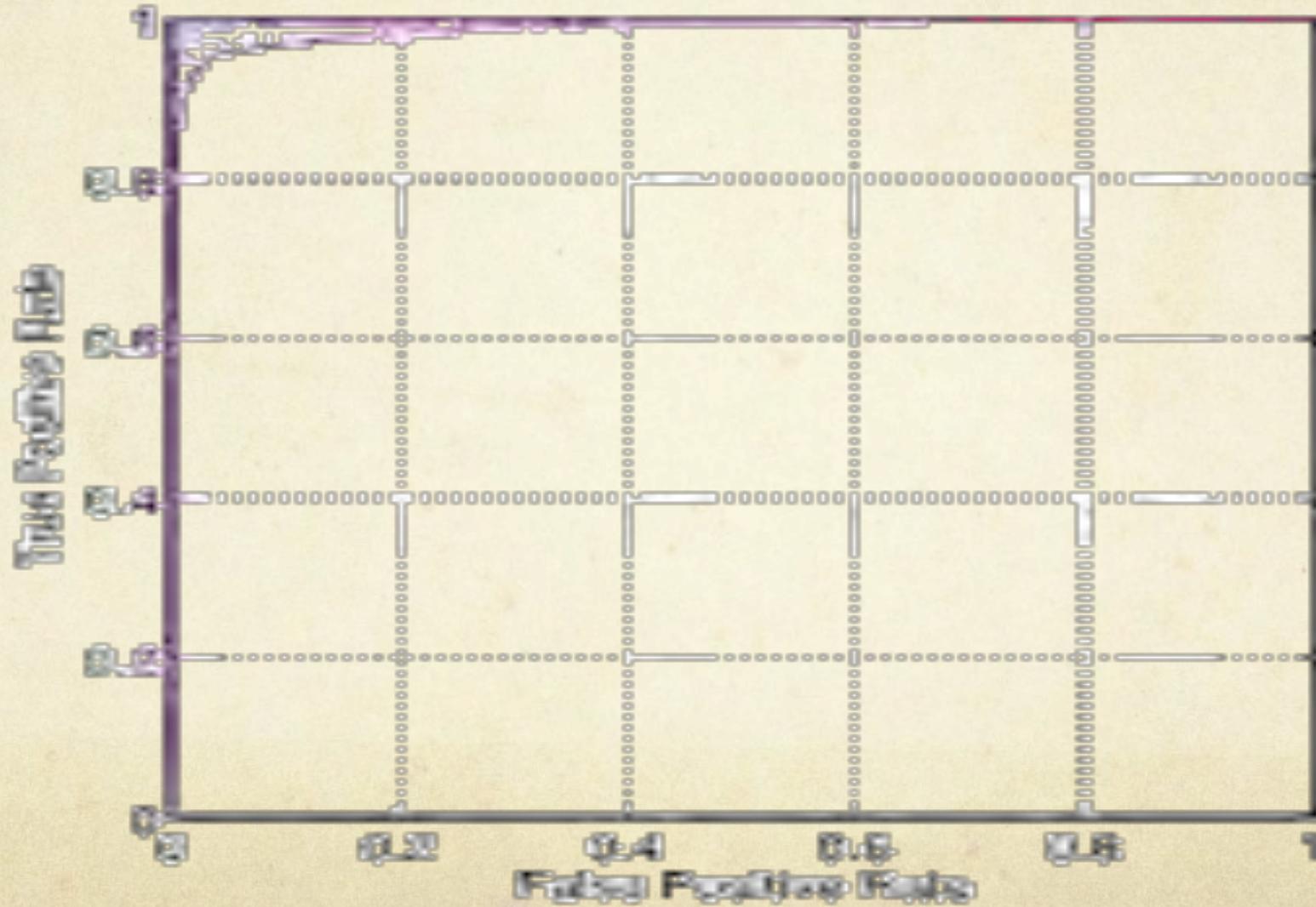
□ On-going Work

- ✦ Compare usability among 3D signatures and existing authentication methods
- ✦ Study other types of 3D signatures

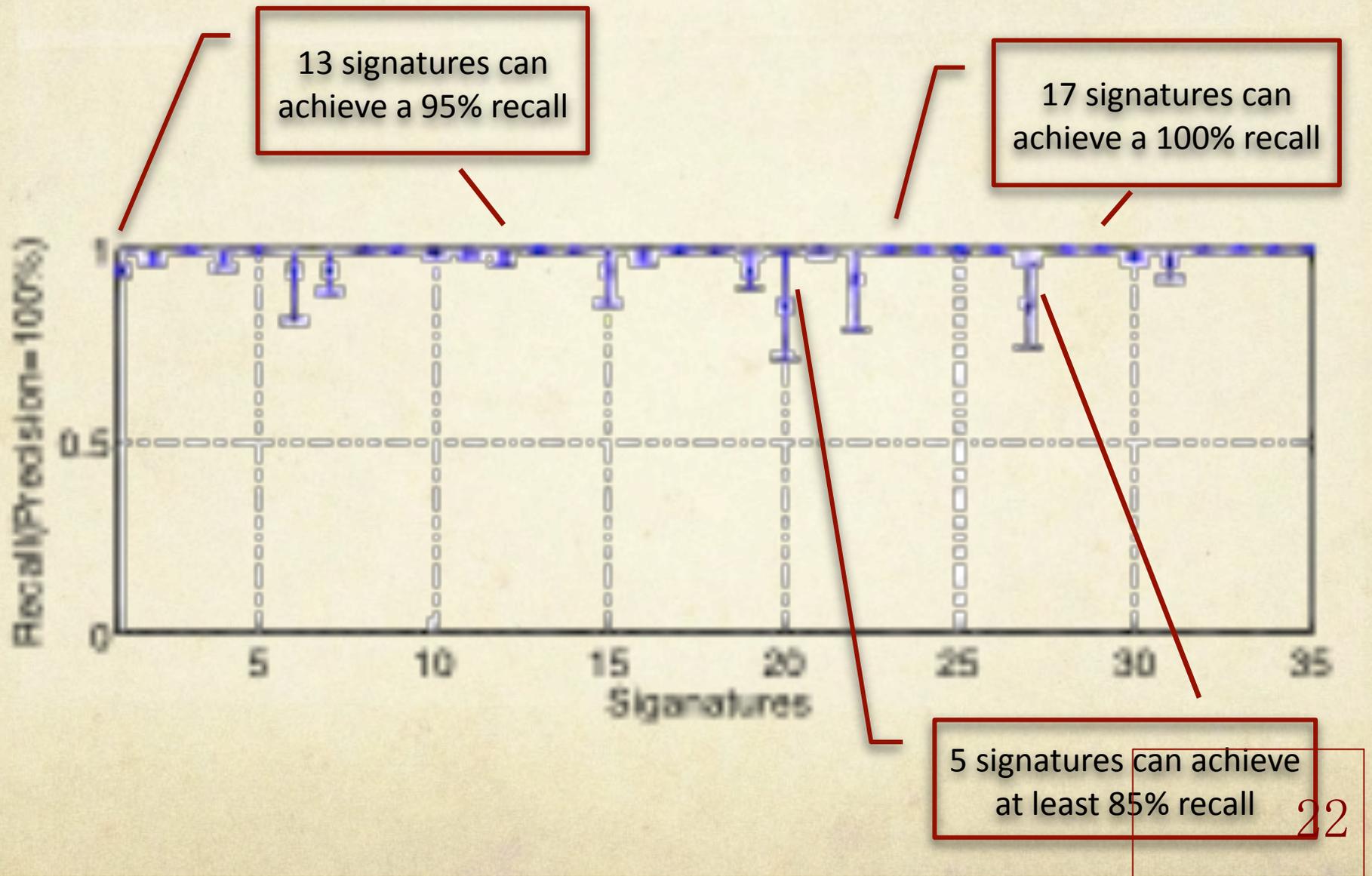
Thank you!

Questions?

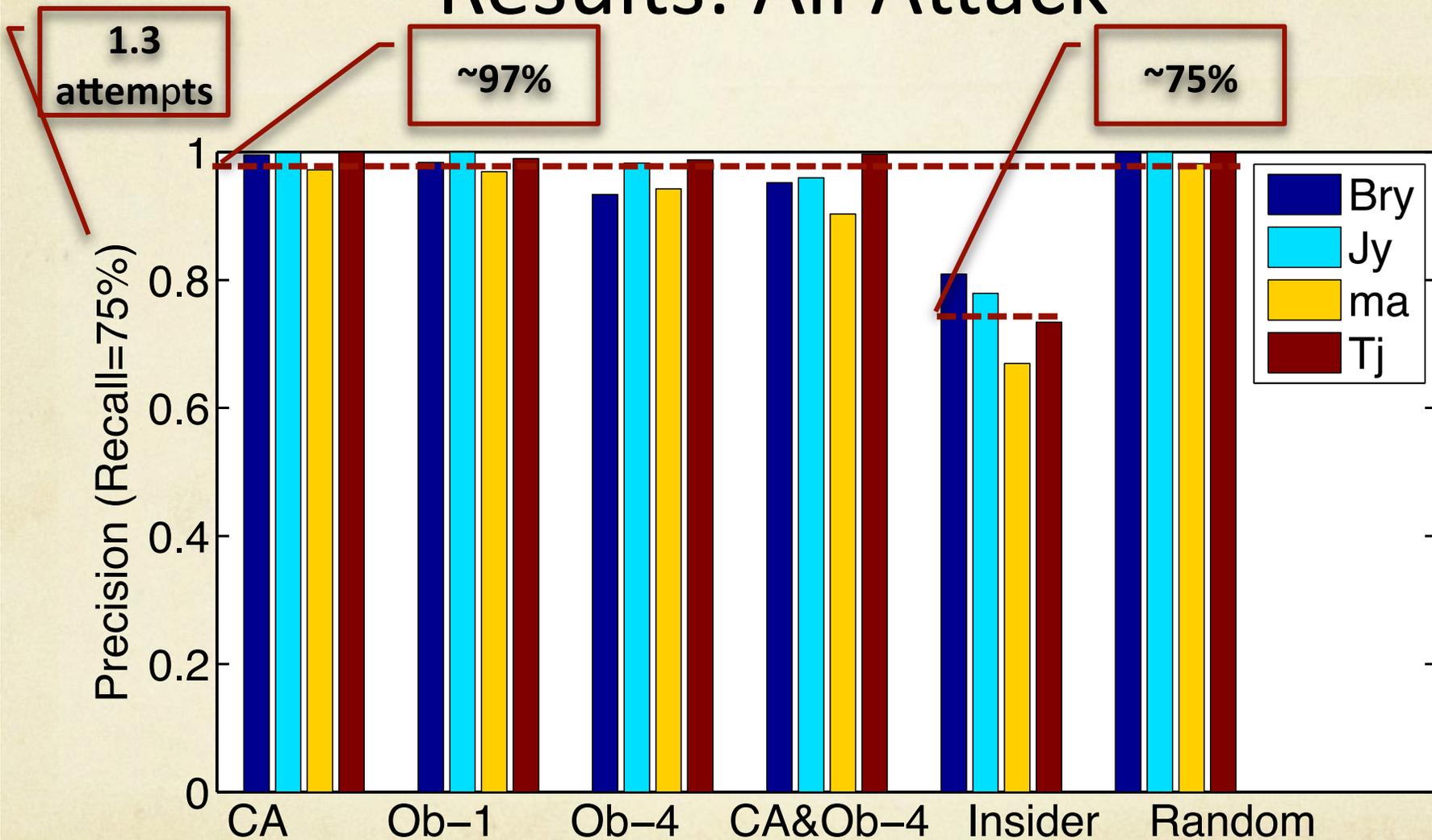
ROC Curves



Results: Legitimate User



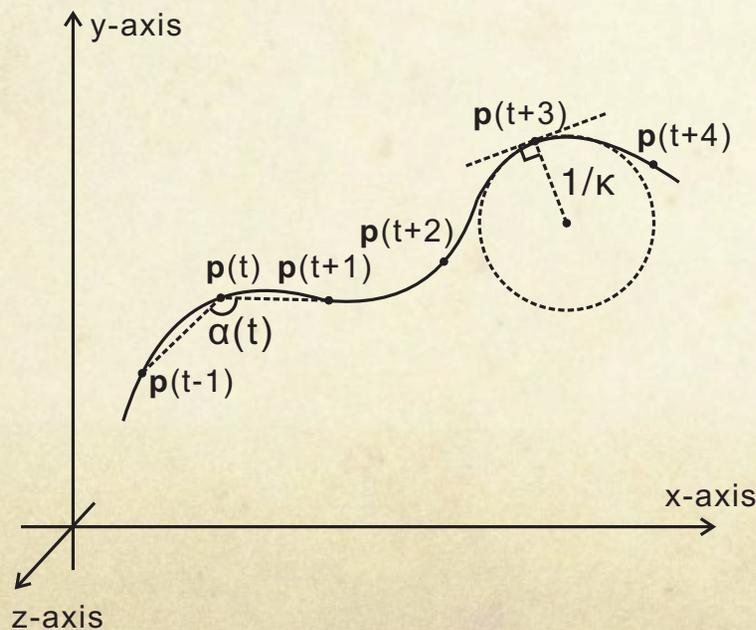
Results: All Attack



(b) Achievable precision at a 75% recall

How to Select a Feature

- ❑ We choose features based on the movements and geometries on the signature trajectories.
- ❑ Also we also learnt from the results on 2D online signature verification.



An illustration of path angle and curvature

Related Work

- ❑ This is basically a signature verification problem, which is based on research on 2D online signature.
- ❑ And also it is a behavior biometrics method, which is also related to gesture recognition and classification;
- ❑ while it is also a new way of Kinect application.

How to Select Template & Threshold

- ✦ **Template** Selection

 - ◇ The template has the minimum DTW distance to others

- ✦ **Threshold** Selection

 - ◇ Select a threshold that leads to a zero false positive rate among training samples.