## WIP: Practical Removal Attacks on LiDAR-based Object Detection in **Autonomous Driving**

Takami Sato\*, Yuki Hayakawa\*, Ryo Suzuki\*, Yohsuke Shiiki\*, Kentaro Yoshioka, and Qi Alfred Chen



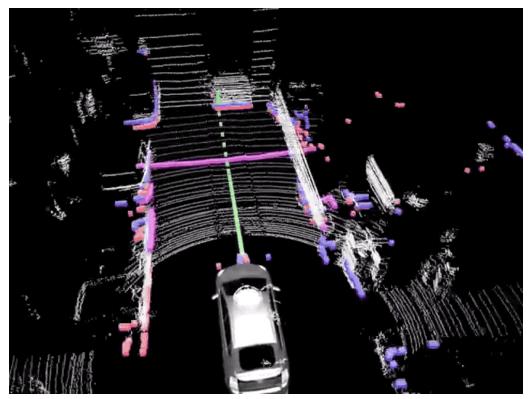




#### LiDAR plays an essential role in Autonomous Driving (AD)

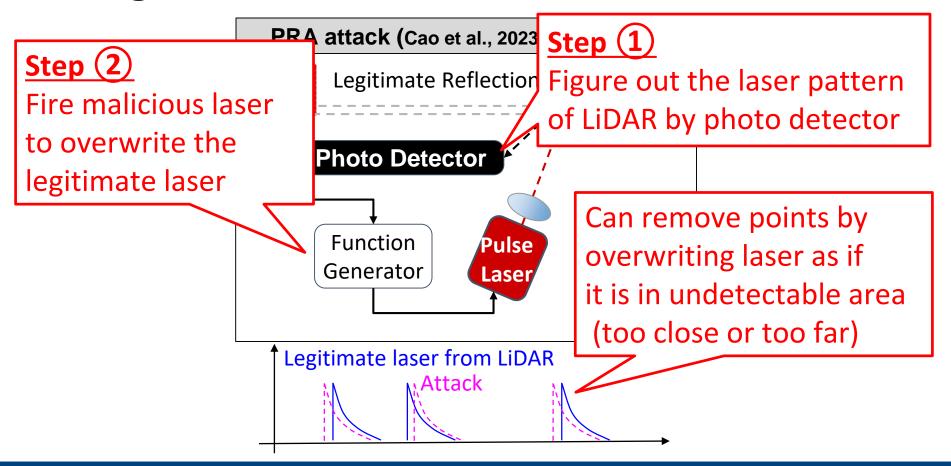






Current Level-4 AD heavily relies on LiDAR sensing for object detection

## Existing Removal Attack: PRA attack



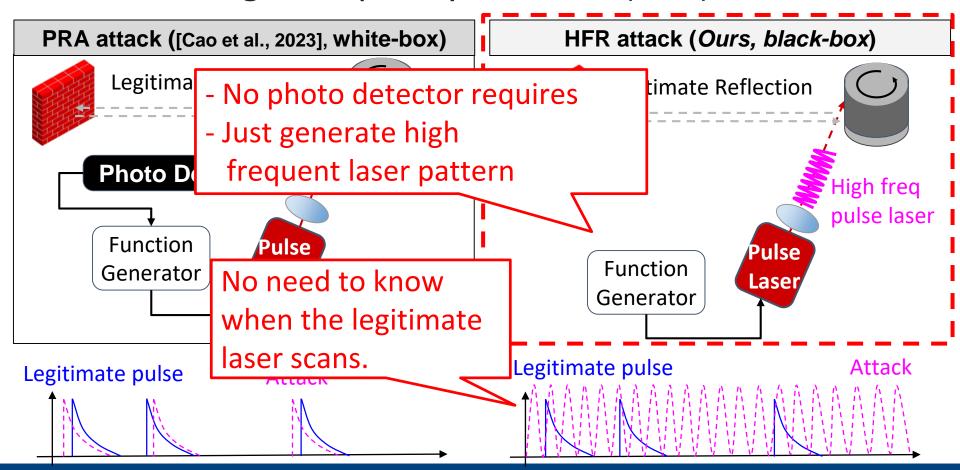
### Existing Removal Attack: PRA attack

#### **Limitation of PRA Attack**

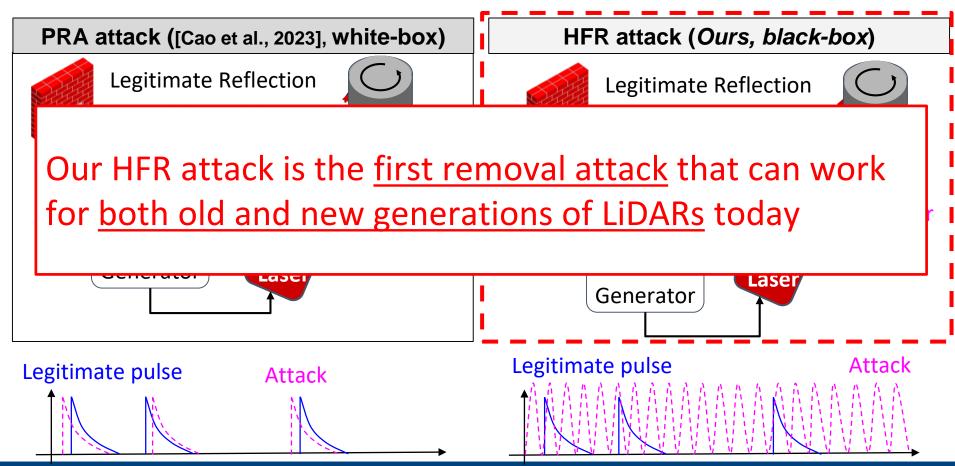
- Need white-box knowledge on LiDAR scan Pattern
- Defensible by randomizing the scan pattern
  - 5 out of 6 new generation of LiDARs we were able to access have the laser timing randomization
  - State-of-the-art prior attacks can only work for 1st-generation LiDARs, not the new generation ones



#### Our Attack: High-Frequency Removal (HFR) Attack

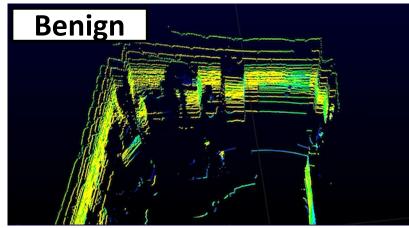


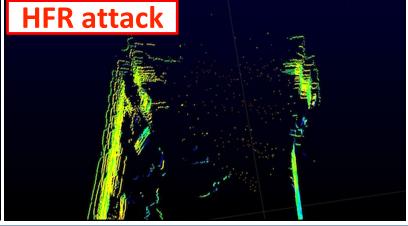
#### Our Attack: High-Frequency Removal (HFR) Attack



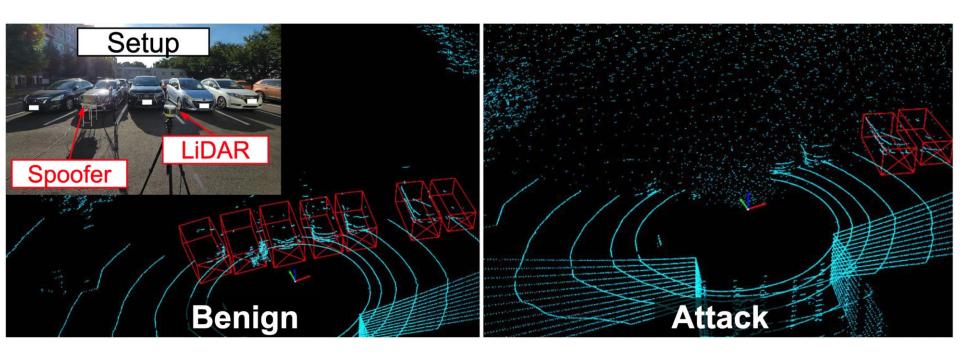
## HFR Attack Indoor Demo





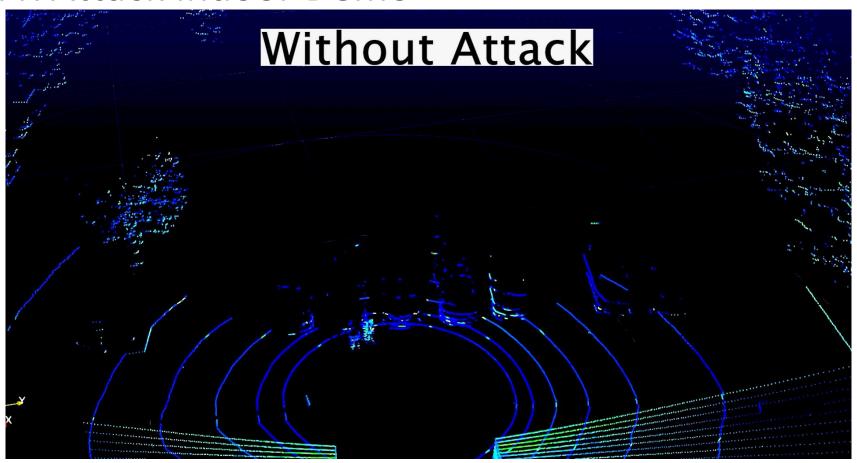


#### HFR Attack Outdoor Demo



5 cars are not detected by Apollo 6.0's PointPillars object detector

### HFR Attack Indoor Demo



## Take Away & Future Plan

- Design HFR attack, which is the first black-box removal attack that can be effective against next-gen LiDARs with timing randomization
- HFR can remove ~75% of points in the attack area on a next-gen LiDAR

#### **Future Plan**

- Large-scale Measurement Study on Multiple Next-Gen. LiDARs
  - How are next-gen. LiDARs robust against LiDAR spoofing attacks?
- Evaluation against Moving Vehicle
  - Can be effective against end-to-end autonomous driving scenarios?
- Defense Evaluation
  - Can design effective defense for HFR attack?

# Thank you!



For more details, please check out our paper



<u>A</u>utonomous & <u>S</u>mart <u>S</u>ystems <u>Guard</u> Research Group



