

HoneySat: A Network-based Satellite Honey-pot Framework

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**Equal Contribution*

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Deception with Honeypots

- **Lures attackers** into controlled, instrumented decoys
- **High-interaction “mission realism”**: Real ground tools + realistic interfaces
- Detecting presence (and methods) of Attackers
- Honeypots often mimic key behaviors, not the full real system
- **We need a realistic decoy that doesn't require mission-specific internals and doesn't reveal how the real mission works**



Motivation



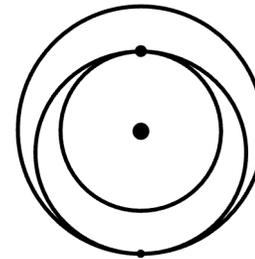
Viasat KA-SAT

Feb. 2022

APT Targeting
Multiple Companies

TIDRONE

Sep. 2024



STARLINK

**Starlink Infrastructure
Breach Attempts**

Early 2025



GPS Spoofing

Aug. 2025



Motivation

- **RoSAT** X-ray astronomy satellite launched in 1990



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- **Permanent damage to onboard systems**



Motivation

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- A **network intrusion** into systems associated with NASA/GSFC was **documented**
- **Permanent damage to onboard systems**
- **How are these incidents connected?**



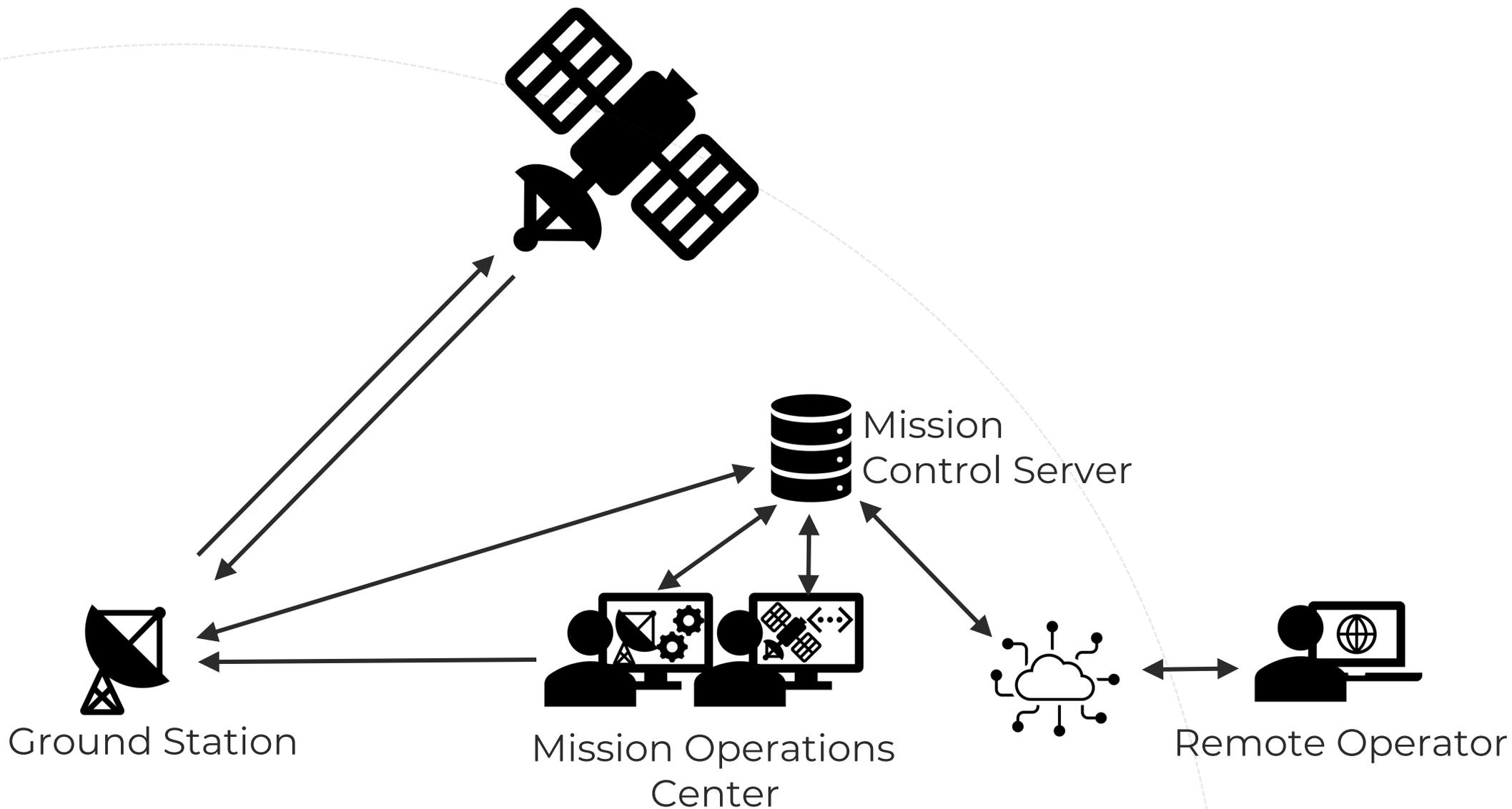
Objectives

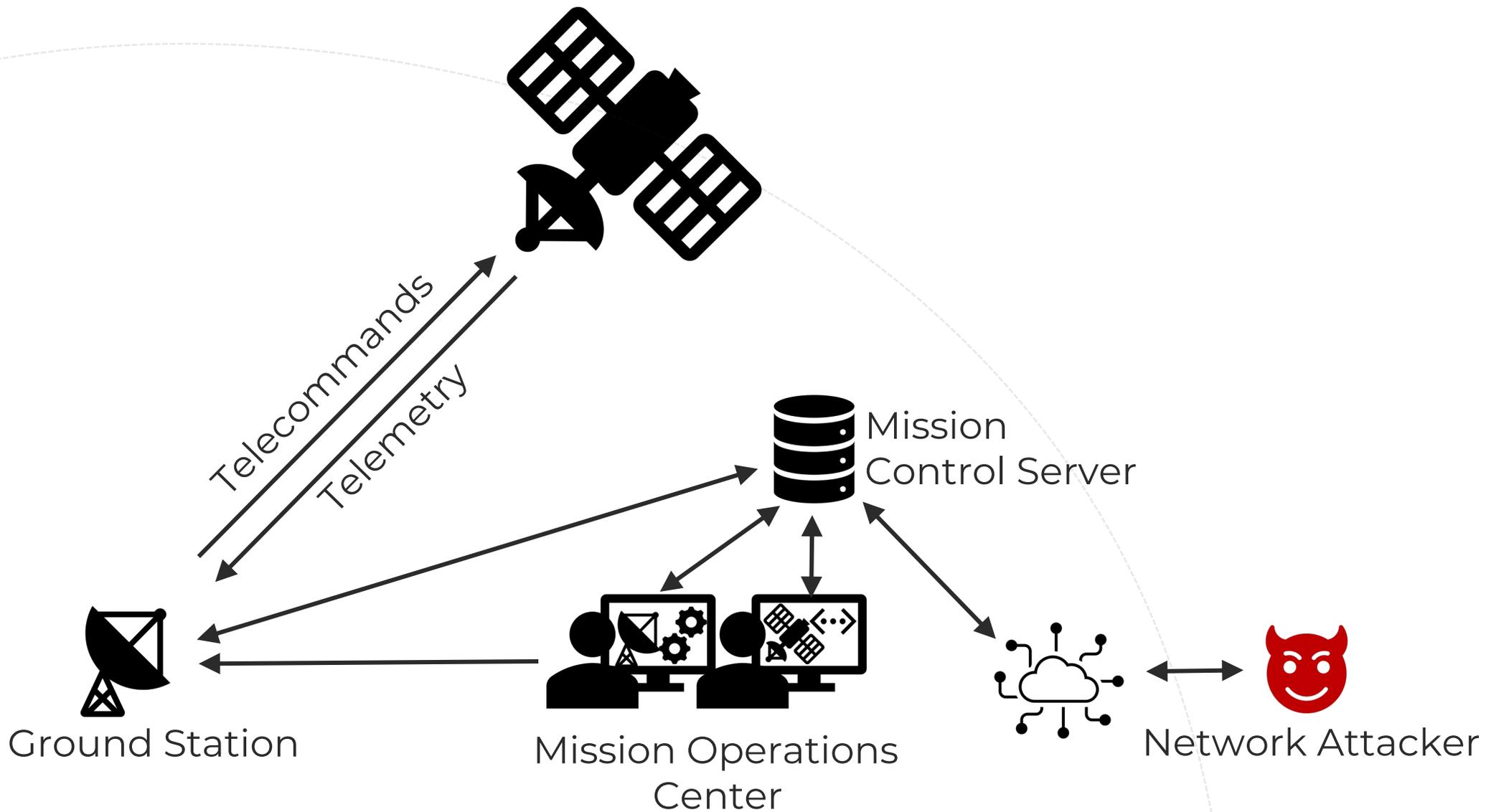
*Design Objectives of a Satellite
Honeypot*

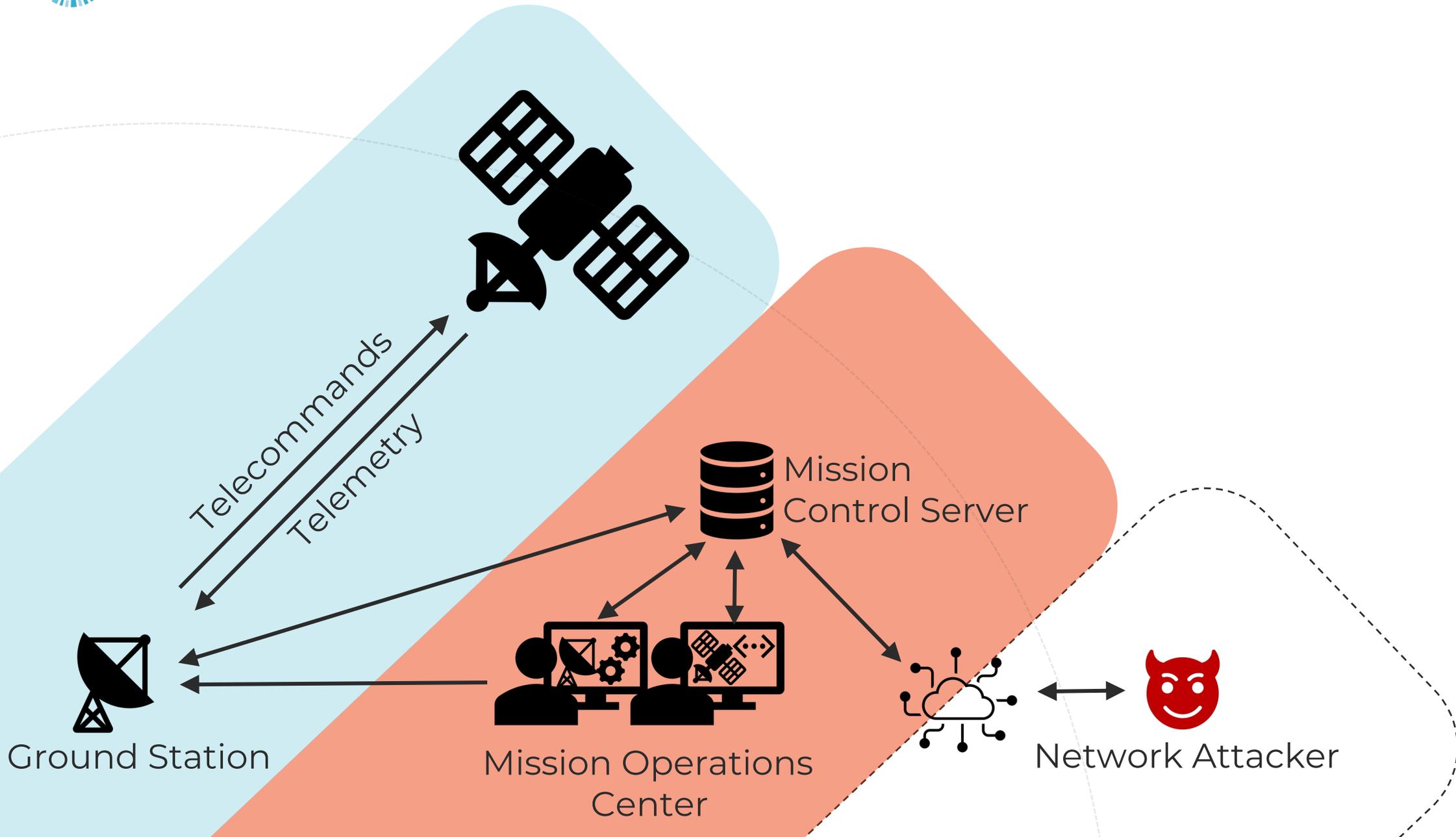
- I. Capture Rich interaction Data
- II. Deception
- III. Extensibility and Customizability



Overview

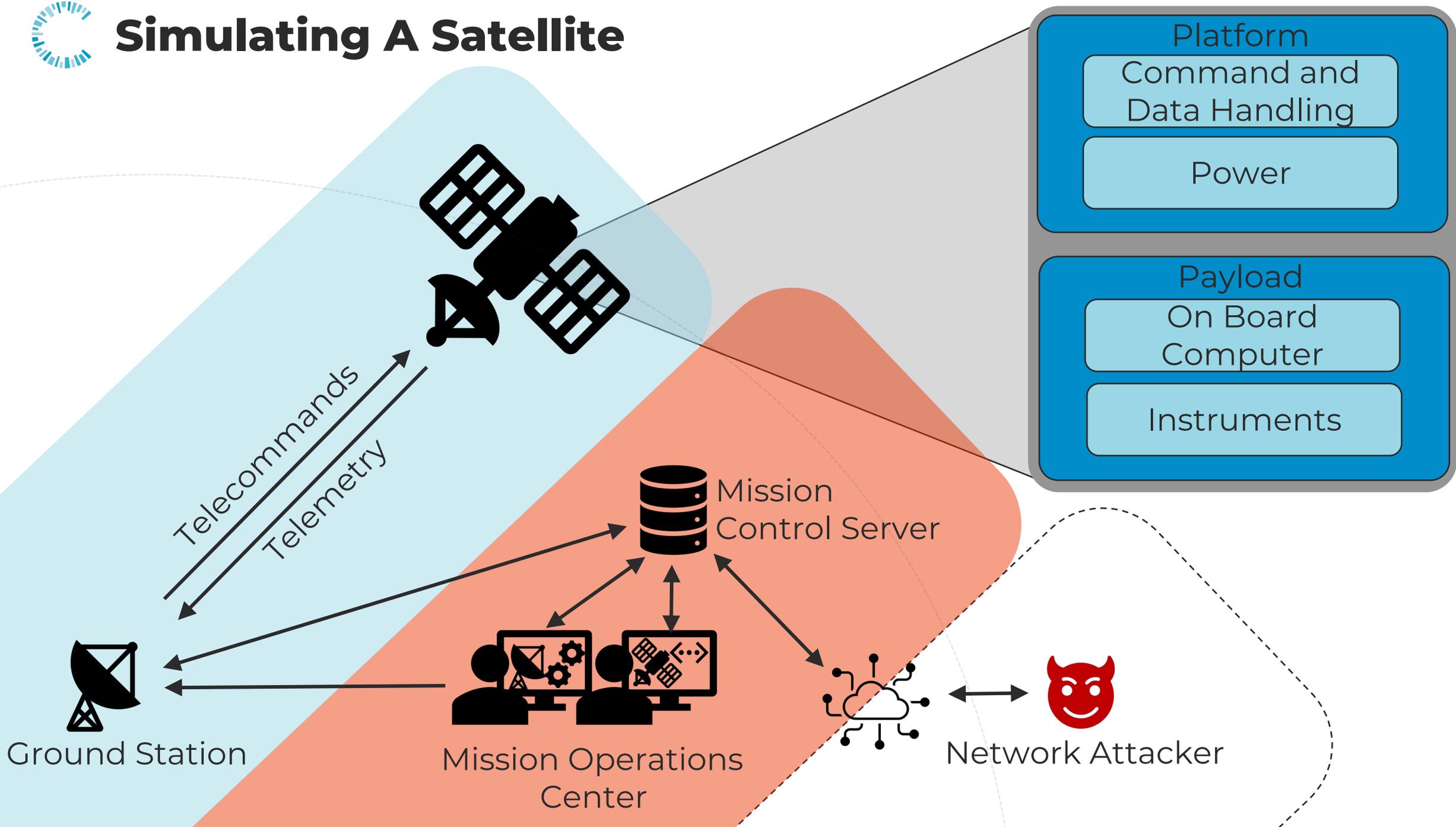






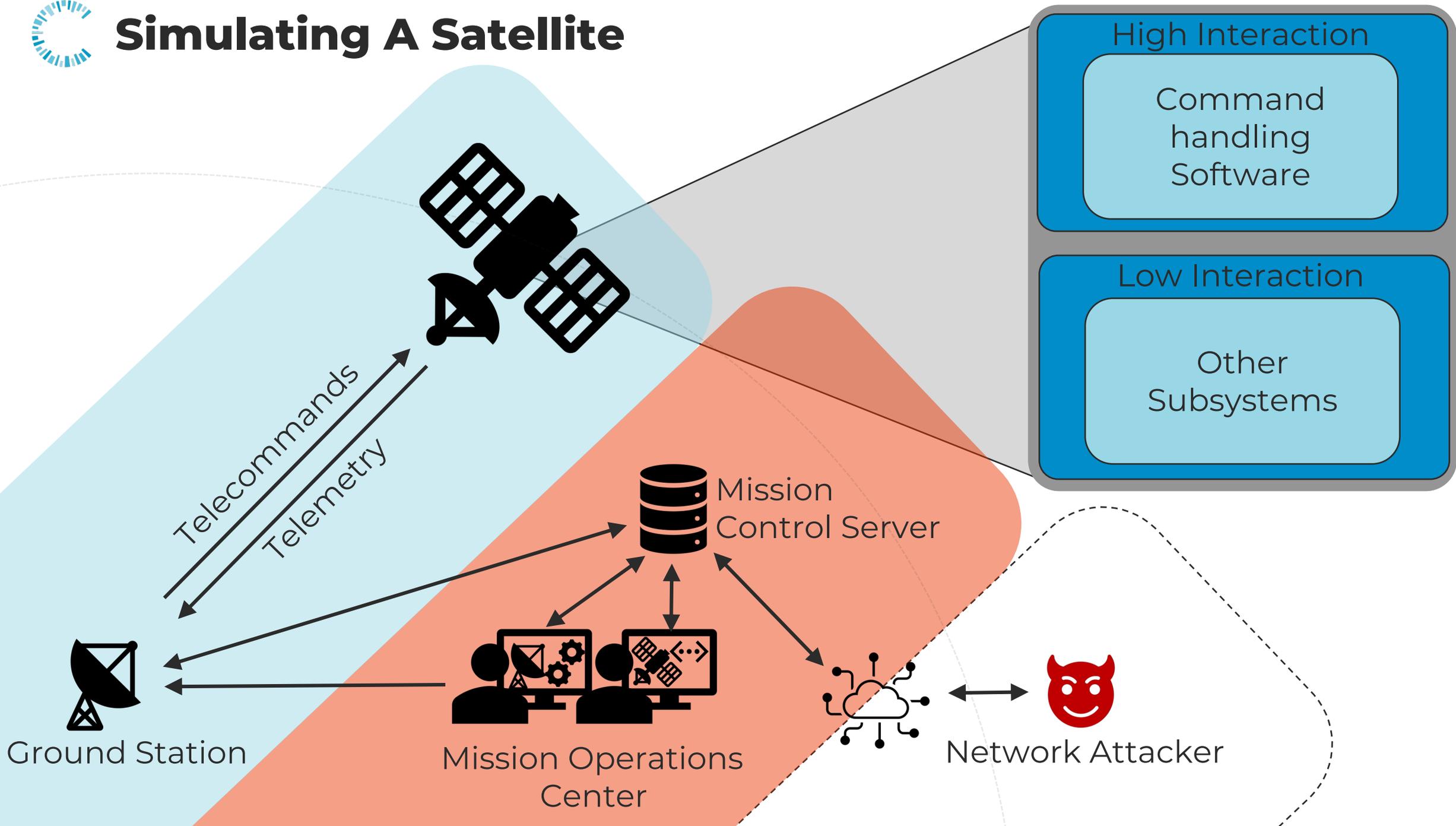


Simulating A Satellite



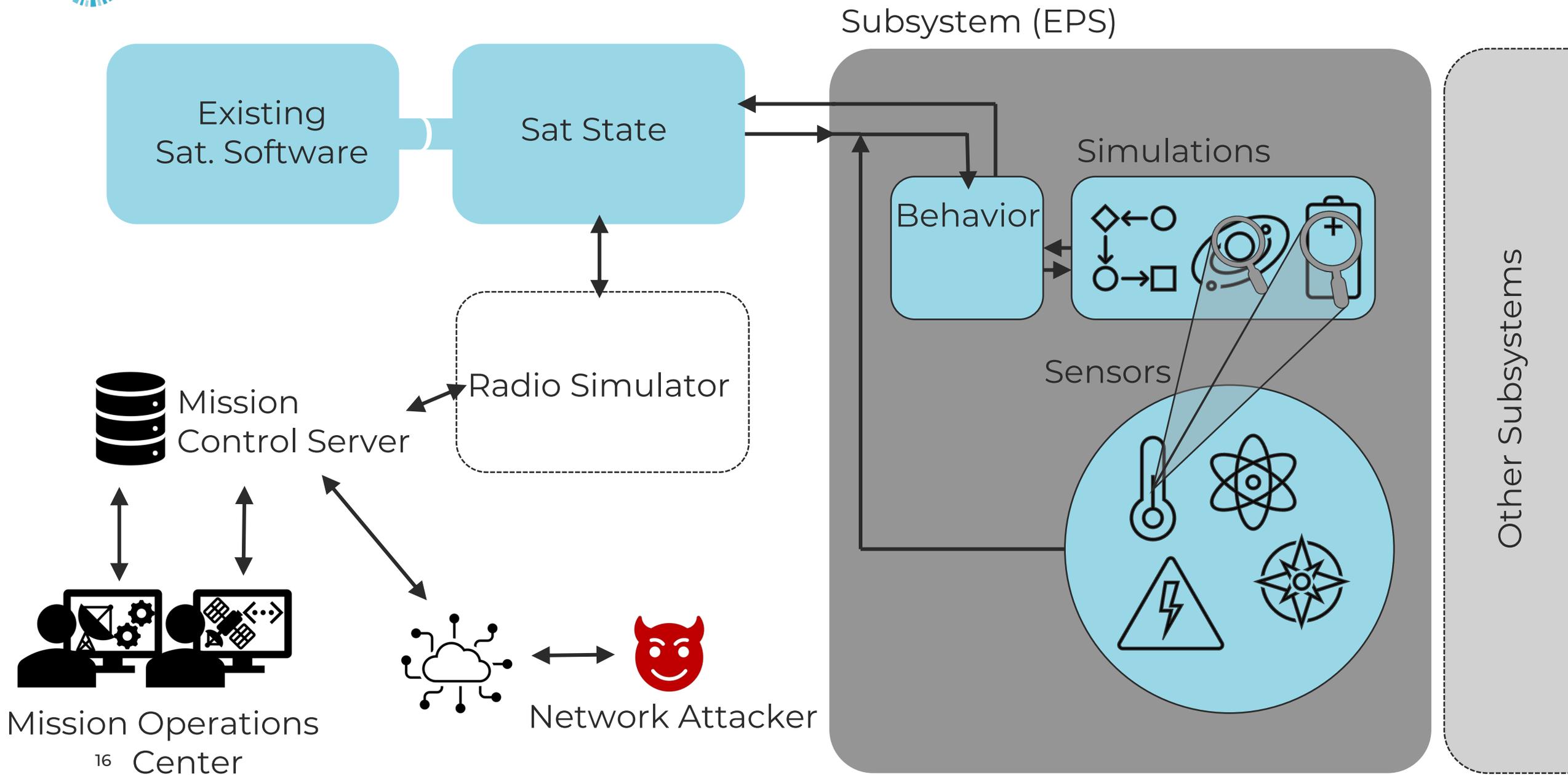


Simulating A Satellite





Delivering Believable Spacecraft



Subsystem (EPS)

Simulations

Behavior

Sensors

Other Subsystems

Mission Control Server

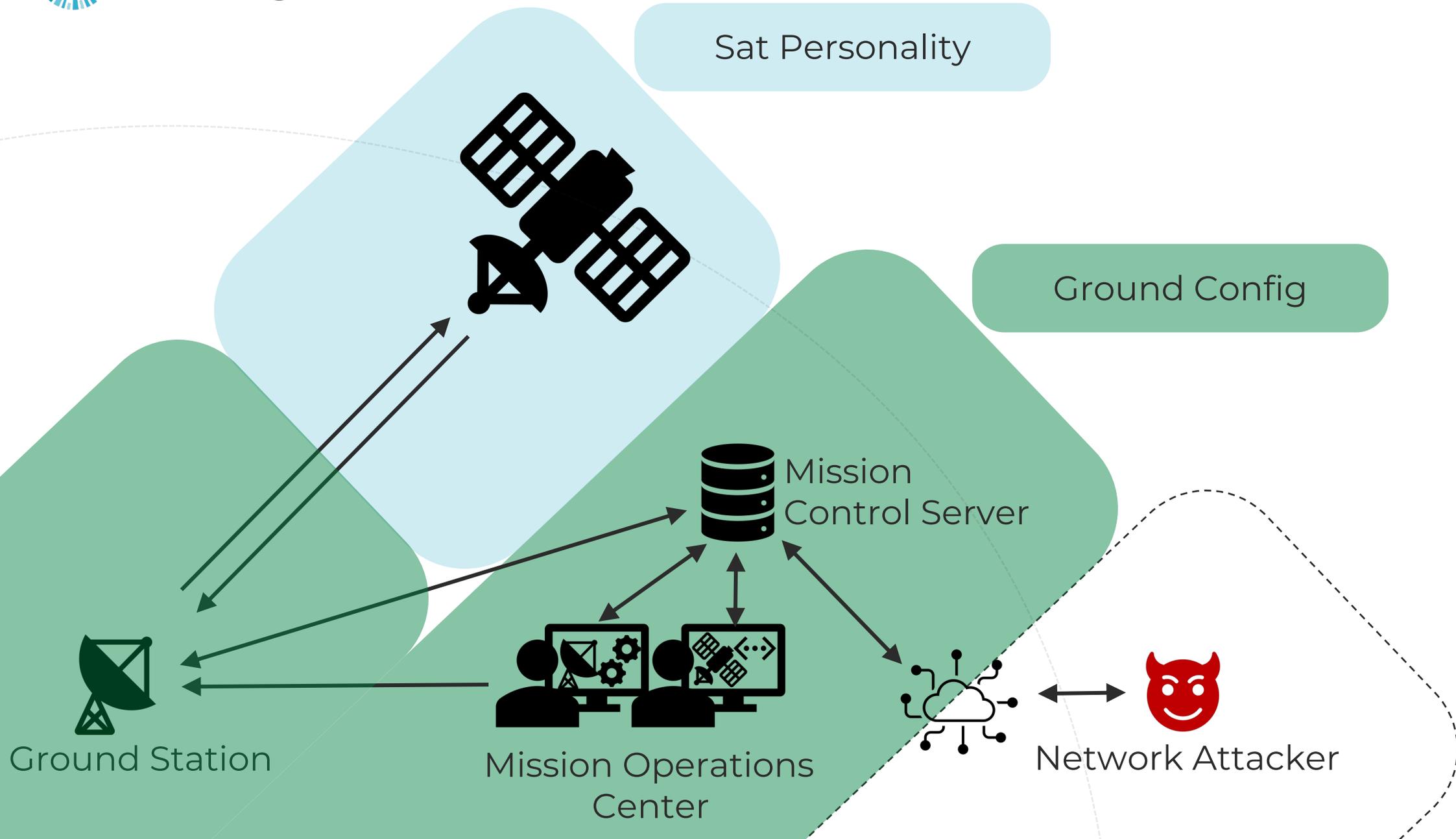
Radio Simulator

Mission Operations

Network Attacker



Configuration





Delivering Believable Ground Infrastructure

- Operator **workstation** with Remote Desktop



Delivering Believable Ground Infrastructure

- Operator **workstation** with Remote Desktop
- Network with **Mission Control Server** and **Ground Station**



Delivering Believable Ground Infrastructure

- Operator **workstation** with Remote Desktop
- Network with **Mission Control Server** and **Ground Station**
- **Mission Control Client**



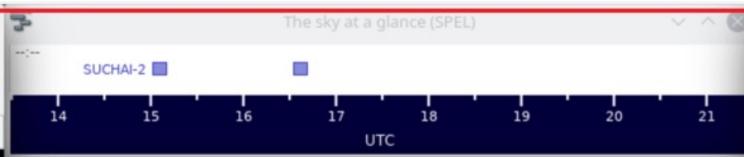
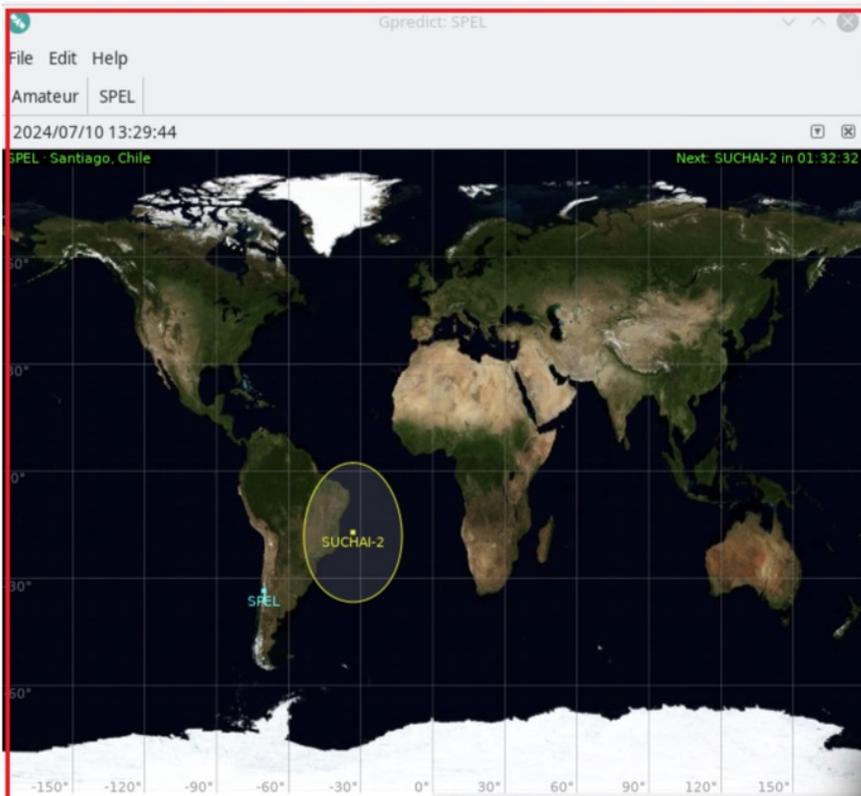
Delivering Believable Ground Infrastructure

- Operator **workstation** with Remote Desktop
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- **Mission Control Client**
- **Ground Station Control Software**



Delivering Believable Ground Infrastructure

- Operator **workstation** with Remote Desktop
- Network with **Mission Control Server** and **Ground Station**
- **Mission Control Client**
- **Ground Station Control Software**
- **Standard** Operational **tools** bundled for Realism



Gpredict Radio Control: SPEL

Downlink

▲▲▲▲▲▲▲▲▲▲

4 3 7.2 3 0.0 0 0 Hz

▼▼▼▼▼▼▼▼▼▼

Doppler: 7185 Hz LO: 0 MHz

Radio: 145.890.000 Hz

Uplink

▲▲▲▲▲▲▲▲▲▲

4 3 7.2 5 0.0 0 0 Hz

▼▼▼▼▼▼▼▼▼▼

Doppler: -7185 Hz LO: 0 MHz

Radio: 145.890.000 Hz

Target: SUCHAI-2 [Track] [T] [L]

Az: 73.73° Range: 4159 km
El: -13.31° Rate: -4.926 km/s

Settings: 1. Device: SPEL-GS [Engage] 2. Device: None Cycle: 1000 msec

AOS in 01:32:29

Upcoming passes for SUCHAI-2

| AOS | LOS | Duration | Max El | AOS Az | LOS Az |
|---------------------|---------------------|----------|--------|---------|---------|
| 2024/07/10 15:02:14 | 2024/07/10 15:11:14 | 00:09:00 | 18.01° | 42.75° | 172.55° |
| 2024/07/10 16:33:49 | 2024/07/10 16:42:20 | 00:08:30 | 12.79° | 333.85° | 215.31° |
| 2024/07/11 03:48:50 | 2024/07/11 03:58:19 | 00:09:29 | 23.55° | 154.10° | 11.77° |

[Print] [Save] [Close]

Gpredict Rotator Control: SPEL

Azimuth: 42.75°

Elevation: 0.00°

Read: ---

Target: SUCHAI-2 [Track]

Az: 73.73° El: -13.31° ΔT: 01:32:29

Settings: Device: SPEL-GS [Engage] Monitor Cycle: 1000 msec Tolerance: 3.00 deg

SPEL

Next: SUCHAI-2 in 01:32:29

SUCHAI-2

- Azimuth : 73.73°
- Elevation : -13.31°
- Slant Range : 4159 km
- Range Rate : -4.926 km/sec
- Next Event : AOS: 2024/07/10 15:02:14
- SSP Loc. : HH32
- Footprint : 4335
- Altitude : 387 km
- Velocity : 7.679
- Doppler@100M : 1643
- Sig. Loss : 144.7
- Sig. Delay : 13.87
- Mean Anom. : 7.17°
- Orbit Phase : 10.08
- Orbit Num. : 12733
- Visibility : Daylight

Serial Commander

Archivo Herramientas Ayuda

Conexión: IP: 172.17.58.76, Puerto: 8001

Opciones: Agregar marca de tiempo, Auto scroll

Lista de comandos:

- trx_send_beacon
- trx_read_reg <registro>
- trx_tm <funcion>
- trx_getstatustrx_set_beacon [<text>]
- trx_set_mode <mode>
- trx_set_tm_pwr <pwr>
- trx_set_bc_pwr <pwr>
- trx_read_tc_frame

[Eco] LF CR [Enviar]

telnet - Konsole

```

log_set %d %d %d
fp_set_cmd %d %d %d %d %d %d %d %s %n
fp_set_cmd_unix %d %d %d %s %n
fp_set_cmd_dt %d %d %d %s %n
fp_del_cmd %d %d %d %d %d
fp_del_cmd_unix %d
fp_show
fp_reset
fp_purge
com_ping %d
com_send_rpt %d %s
com_send_cmd %d %n
com_send_tc %d %n
com_send_data %d %d %n
com_debug
com_set_time_node %d
tm_parse_status
tm_parse_string
tm_send_status %d
tm_send_var %d %s
tm_get_last %u
tm_get_single %u %u
tm_send_last %u %u
tm_send_all %u %u
tm_send_n %u %u %u
tm_parse_payload %
tm_set_ack %u %u
tm_send_cmds %d
tm_send_fp %d
tm_print_fp
tm_dump %d %s
tm_send_file %s %d
tm_parse_file
tm_send_file_part %s %d %d %d %d
tm_merge_file %s %d
tm_ls %s %d
obc_get_sensors
obc_update_status
obc_set_mode %s
obc_cancel_deploy
tm_send_msg %d %n
tm_parse_msg
tm_send_beacon %d
tm_parse_beacon
tle_send %d %s

```

[IN 0][1720618158][Executer] Command result: 1



Evaluation

- **10 experienced** SmallSat **operators** (1–10 years; 1–5 missions; diverse regions/sectors)
- **Overall realism:** 90% agreed they “would not be able to distinguish” HoneySat from the real mission.
- We support interactions for **33 / 38 SPACE-SHIELD techniques**



Point of Entry

- Website with **weak credentials** as initial **entry point**
- **Multiple entry styles** tested:
 1. Web-based mission control interface
 2. Ground-station appliance config page
 3. Internal “mission” website
- **Best-performing lure**: a Django based mission-style website with documentation + remote-desktop credentials to entice access



Deployments

| Deployment | Sat. Personality | Real Mission Owner | HoneySat Region | Duration (months) |
|-------------------|-------------------------|---------------------------|------------------------|--------------------------|
| Cloud | PIXL-1 | DLR | Germany | 6 |
| Cloud | PIXL-1 | DLR | Germany | 6 |
| Cloud | ACS3 | NASA | USA | 6 |
| Cloud | ACS3 | NASA | USA | 6 |
| On-prem | SUCHAI-2 | SPEL | University of Chile | 12 |



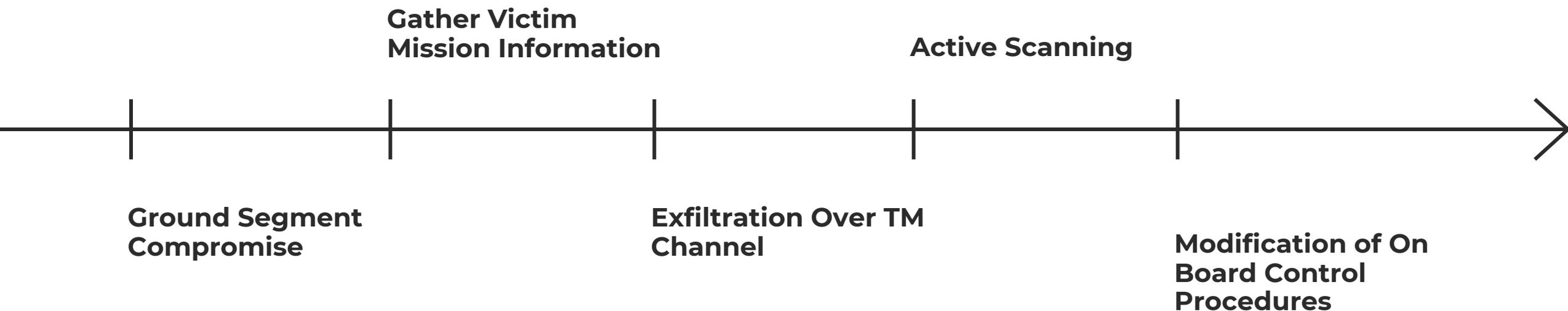
Interactions

| Date | Mission | HoneySat Region | Attacker Geo IP |
|--------------|----------------|------------------------|------------------------|
| Jan 18, 2025 | ACS3 | USA | Egypt |
| Jan 24, 2025 | PIXL-1 | Germany | Tor |
| Jan 24, 2025 | ACS3 | USA | Tor |
| Apr 3, 2025 | ACS3 | USA | USA |



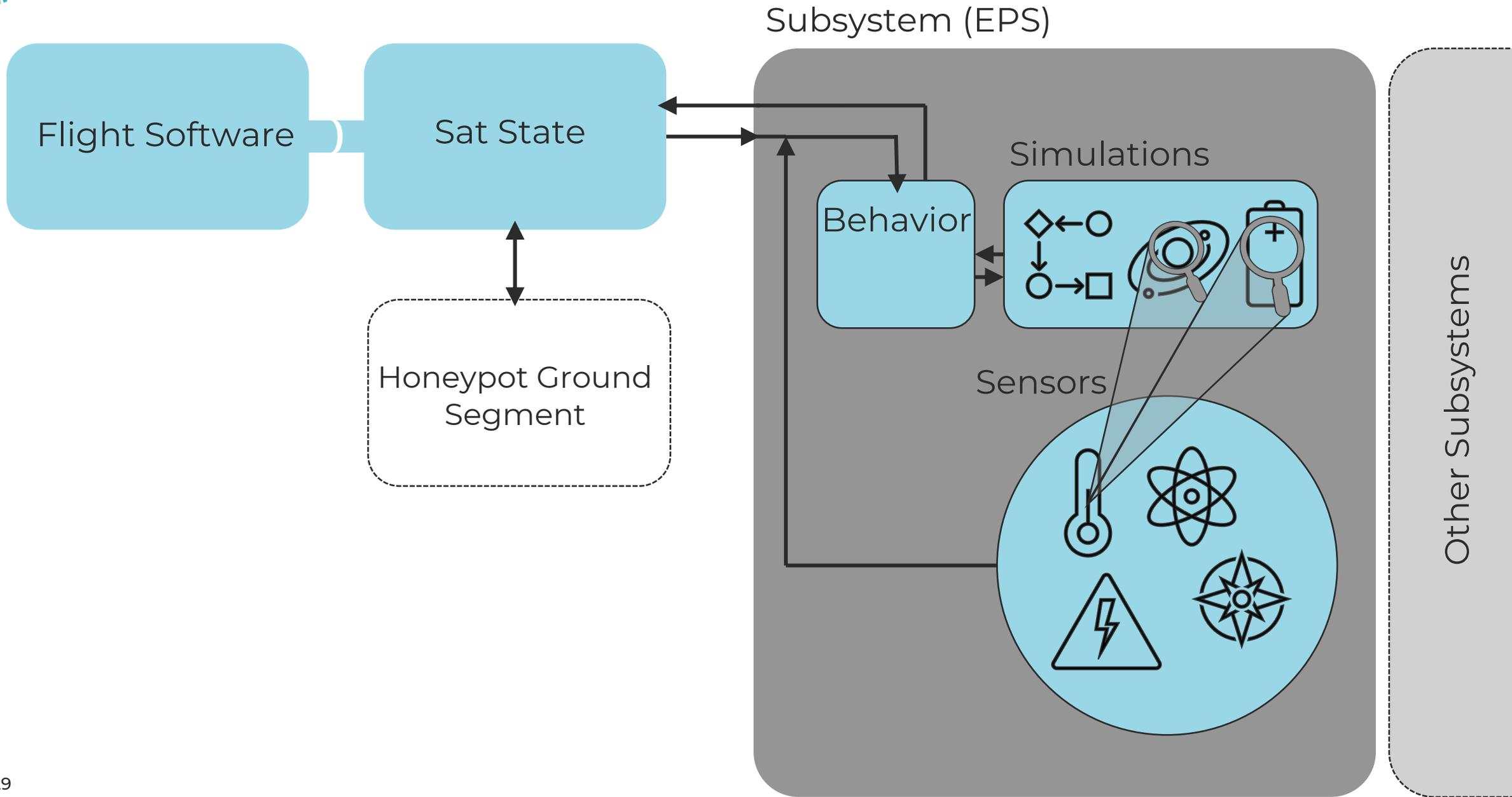
Attacker Behavior

All Attackers interacting with the MCS Performed **Spacecraft's Components Discovery**



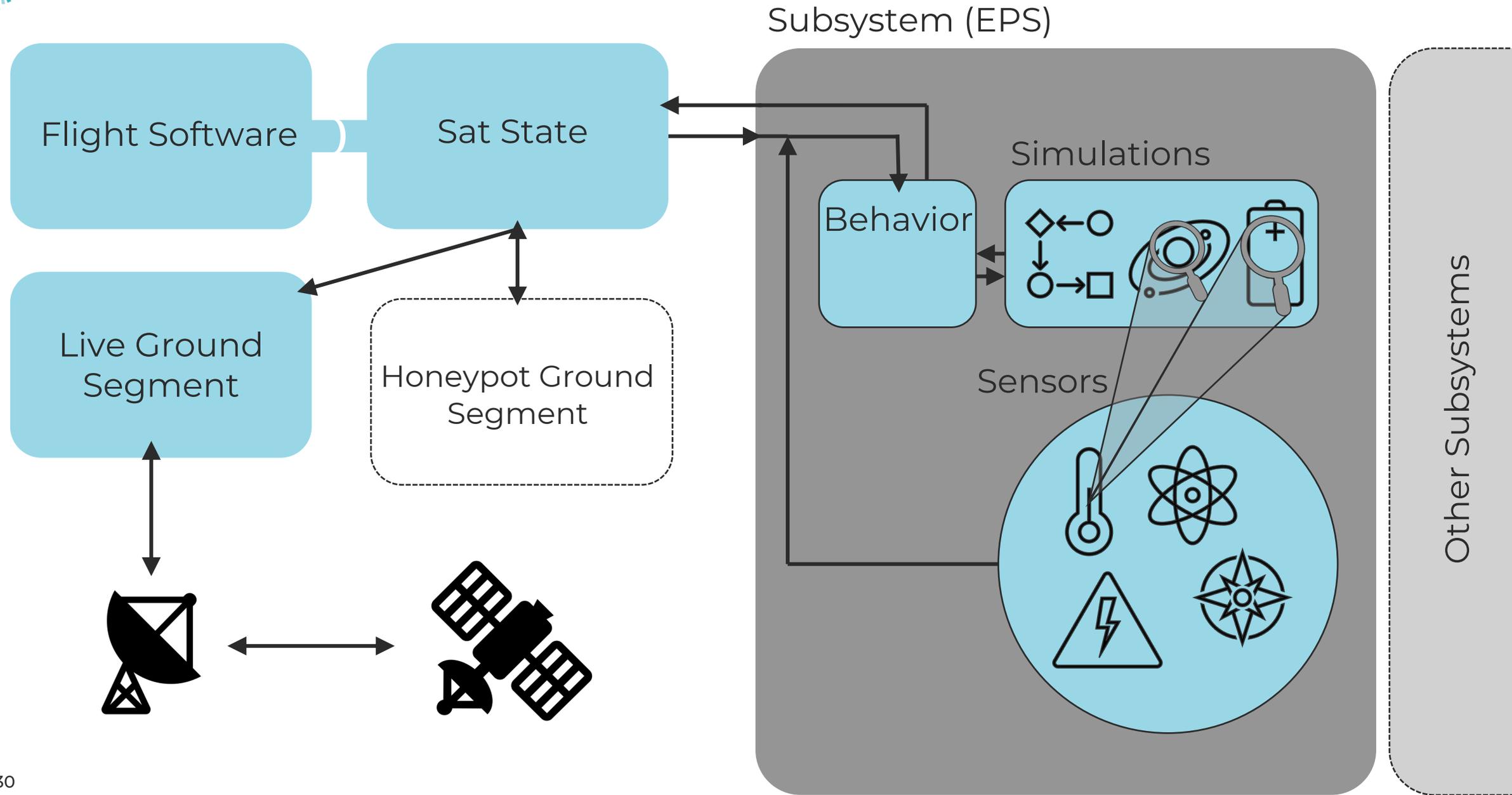


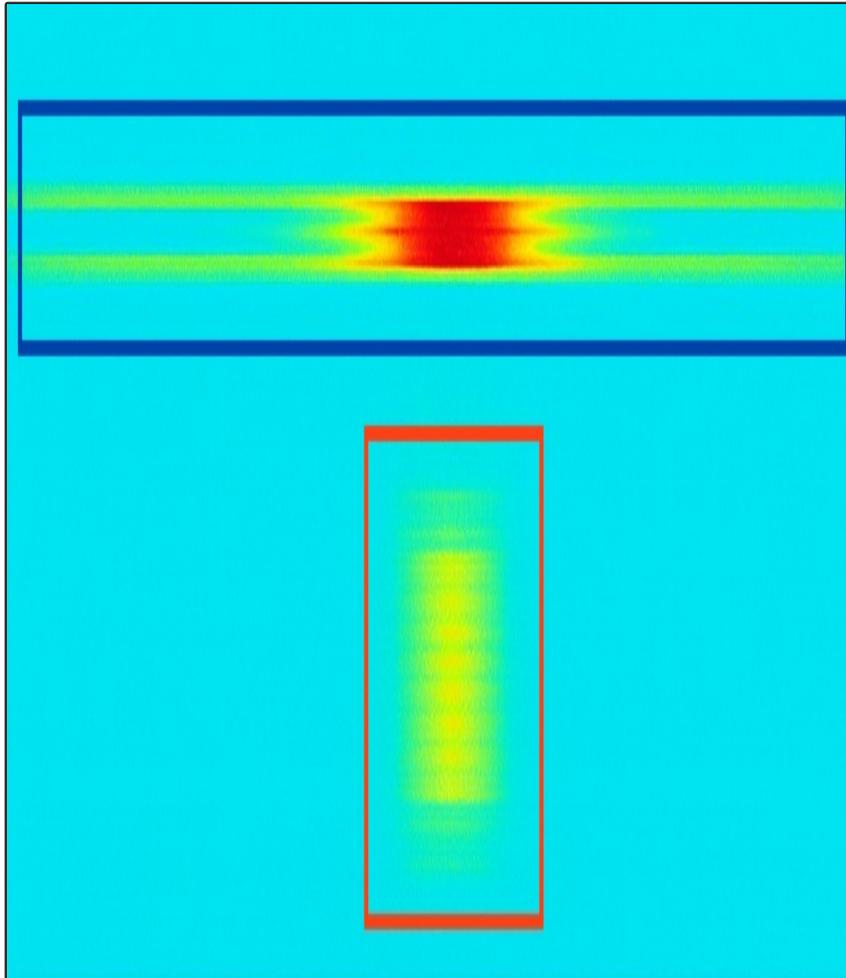
Delivering Believable Spacecraft





Delivering ~~Believable~~ Spacecraft



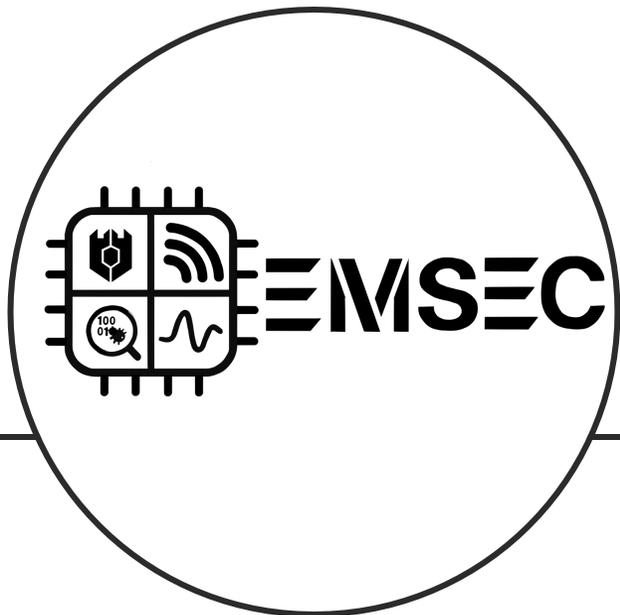


Satellite In The Loop

Deceiving attackers observing the real Ground Station



Q & A



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